

Homotopy

Def- If f and f' are continuous maps of the space X into the space Y , then f is said to be homotopic to f' if there is a continuous map $F: X \times I \rightarrow Y$ such that

$$F(x, 0) = f(x) \quad \text{and} \quad F(x, 1) = f'(x), \quad \forall x \in X$$

Then F is said a homotopy between f and f' and it is denoted by $f \simeq f'$.

Def. If $f \simeq f'$ and f' is a constant map then f is said to be null homotopic.

If t is a parameter representing time, then homotopy F representing continuous deforming of f to f' as t goes from 0 to 1

Def. If f is a continuous map i.e. $f: I \rightarrow X$ such that

$$f(0) = x_0 \quad \text{and} \quad f(1) = x_1,$$

Then f is a path in X from x_0 to x_1 , where x_0 and x_1 are initial and final points of the path

Def. If f and f' are two paths in X then f, f' are said to be path homotopic if f and f' have same initial and final points and if there is a continuous map $F: I \times I \rightarrow X$ such that

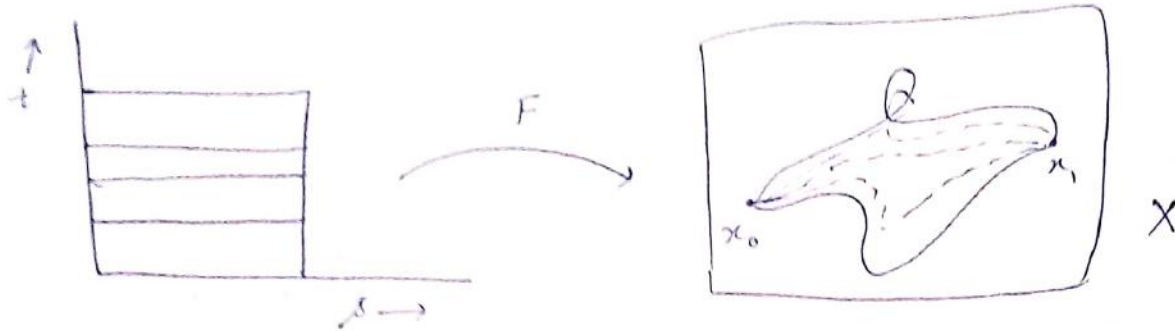
$$F(s, 0) = f(s) \quad \text{and} \quad F(s, 1) = f'(s)$$

$$F(0, t) = x_0 \quad \text{and} \quad F(1, t) = x_1, \quad \forall s \in I$$

and each $t \in I$.

F is said to be Path homotopy between f and f'

If f is path homotopic to f' then $f \simeq_p f'$.



In path homotopy the first condition says that F represents the continuous way of deforming the path f to path f' and second condition says that the end points of the path remain fixed during the deformation.

Equivalence Relation -

The relations \simeq and \simeq_p are path homotopy equivalence relations.

If f is a path then its path homotopy class denoted as $[f]$.

Reflexive - for any map $f: X \rightarrow Y$, define $F: X \times I \rightarrow Y$

$$\text{by } F(x, t) = f(x) \quad (0 \leq t \leq 1)$$

$$F(x, 0) = f(x) = F(x, 1) \quad \forall x \in X$$

$\Rightarrow F$ is required homotopy. If f is path then F is a path homotopy.

Symmetric - let $f \simeq g$ then \exists a homotopy $F: X \times I \rightarrow Y$

$$\text{such that } F(x, 0) = f(x) \quad \text{and} \quad F(x, 1) = g(x) \quad \forall x \in X$$

Now Define a relation function

$$G(x, t) = F(x, 1-t)$$

$$G(x, 0) = F(x, 1) = g(x)$$

$$G(x, 1) = F(x, 0) = f(x)$$

is a homotopy between g and f . $\therefore F$ is a continuous function then G is also continuous hence $g \simeq f$.

If F is path homotopy between f & g then G is a path homotopy bet g & f .

Transitive. If $f \simeq g$ and $g \simeq h$. Then \exists two homotopies F_1 & F_2 as

$$F_1(x, 0) = f(x) \quad \text{and} \quad F_1(x, 1) = g(x)$$

$$F_2(x, 0) = g(x) \quad \text{and} \quad F_2(x, 1) = h(x)$$

$$\text{i.e.} \quad F_1(x, 1) = g(x) = F_2(x, 0).$$

Now to prove that $f \simeq h$.

Define G be a function defined as

$$\text{by the equation, } G(x, t) = \begin{cases} F_1(x, 2t) & , 0 \leq t \leq \frac{1}{2} \\ F_2(x, 2t-1) & , \frac{1}{2} \leq t \leq 1. \end{cases}$$

$$\boxed{G: X \times I \rightarrow Y}$$

The map G is well defined since $t = \frac{1}{2}$

$$\text{Now } F_1(x, 1) = g(x) = G(x, \frac{1}{2})$$

$$F_2(x, 0) = g(x) = G(x, \frac{1}{2})$$

$$\text{Also } G(x, 0) = F_1(x, 0) = f(x)$$

$$G(x, 1) = F_2(x, 1) = h(x)$$

$$\therefore f \simeq h$$

Also G is continuous by pasting lemma.

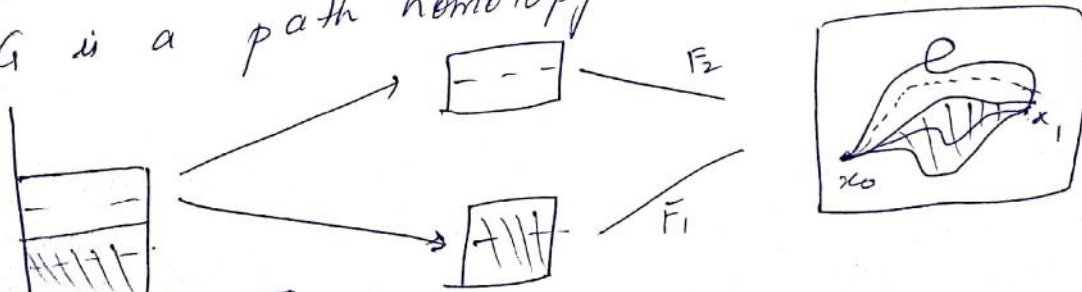
$\because X \times [0, \frac{1}{2}]$ and $X \times [\frac{1}{2}, 1]$ are two closed subsets of $X \times I$ and $\frac{1}{2} \in (X \times [0, \frac{1}{2}]) \cap (X \times [\frac{1}{2}, 1])$

$$\text{and } F_1(x, 1) = F_2(x, 0) = g(x).$$

Then G is continuous.

$\Rightarrow G$ is a homotopy between f & h

If f and g, h are the paths in X then G is a path homotopy between f & h .



Pasting Lemma: Let $X = A \cup B$, where A and B are closed in X . Let $f: A \rightarrow Y$ and $g: B \rightarrow Y$ be continuous. If $f(x) = g(x)$ for every $x \in A \cap B$ then f and g combine to give a continuous function $h: X \rightarrow Y$, defined by setting $h(x) = f(x)$ if $x \in A$ and $h(x) = g(x)$ if $x \in B$. i.e. $h(x) = \begin{cases} f(x) & \forall x \in A \\ g(x) & \forall x \in B \end{cases}$

Proof - Let C be the closed subset of Y . Now

$$h^{-1}(C) = f^{-1}(C) \cup g^{-1}(C)$$

Since f is continuous $\Rightarrow f^{-1}(C)$ is closed in A and \Rightarrow closed in X

Similarly g is continuous $\Rightarrow g^{-1}(C)$ is closed in $B \Rightarrow$ closed in X

$\Rightarrow h^{-1}(C)$ is closed in X .

$\Rightarrow h$ is a continuous function \square

Note \rightarrow The homotopy relation \simeq between mappings of a space into a space Y is an equivalence relation on the space Y^X of all continuous functions.

or, The homotopy relation \simeq gives rise to a partition of the function space Y^X into the disjoint equivalent-classes called homotopy class.

Now we define an operation between two disjoint classes of Y^X
say $[f] * [g] = [f * g]$.

Examples on Homotopy -

(1) Let f and g be two maps of a space X into \mathbb{R}^2 . Then $f \simeq g$ if the map F , is defined by the relation

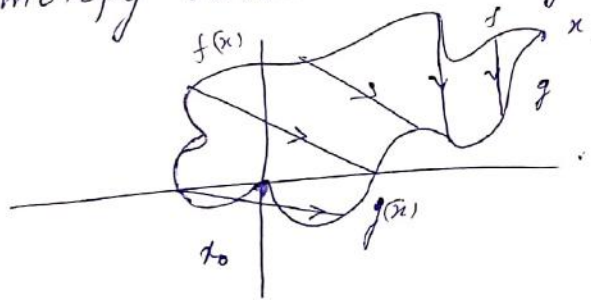
$$F(x, t) = (1-t)f(x) + t g(x)$$

is a homotopy between f and g .

$$\therefore F(x, 0) = f(x), \quad F(x, 1) = g(x)$$

This homotopy is called straight line homotopy because it moves the point $f(x)$ to the point $g(x)$ along the straight line segment joining them.

If f and g are paths from x_0 to x_1 , then F will be path homotopy between f and g . i.e. $f \simeq_p g$.



(2) Let A be a convex subspace of \mathbb{R}^n , i.e. for $a, b \in A$, the st line joining a and b contained in A . Then any two paths f & g in A from x_0 to x_1 , are path homotopic in A , for the st line homotopy F between f and g has image set in A .

(3) Let $X = \mathbb{R}^2 \setminus \{0\}$, a punctured plane. The paths f and g in X are defined by the equations

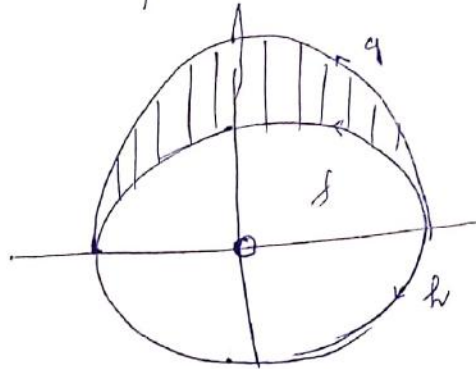
$$f(s) = (\cos \pi s, \sin \pi s), \quad g(s) = (\cos \pi s, 2 \sin \pi s)$$

i.e. $f \simeq_p g$ The straight line homotopy between f and g is acceptable.

But if $h(s) = (\cos \pi s, -\sin \pi s)$ is also a path in X

then there exists no path homotopy between f and h .
 "one cannot deform f past the hole at 0" without introducing a discontinuity.

The paths f and g would be path homotopic if they were paths in \mathbb{R}^2 .



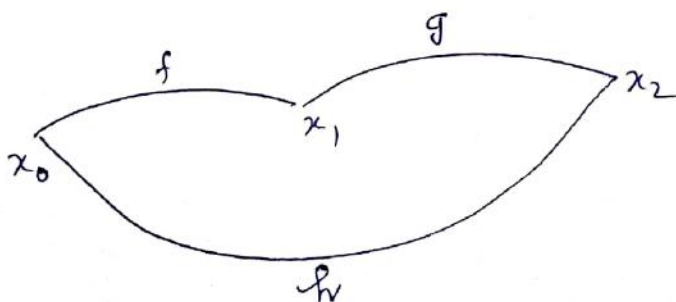
Product of two paths.

If f is a path in X from x_0 to x_1 and g is a path in X from x_1 to x_2 then the product $f * g$ of f and g is defined by path h by the equation.

$$h(s) = \begin{cases} f(2s) & \text{for } s \in [0, \frac{1}{2}] \\ g(2s-1) & \text{for } s \in [\frac{1}{2}, 1] \end{cases}$$

The function h is well defined and continuous by pasting lemma. It is a path in X from x_0 to x_2

" $h(0) = f(0) = x_0$, $h(1) = g(1) = x_2$



The product operation on paths induces a well defined operation on path homotopy classes defined by the equation

$$[f] * [g] = [f * g].$$

Let F be a path homotopy between f and f' and G be a path homotopy between g and g' then

Define
$$H(s, t) = \begin{cases} F(2s, t) & s \in [0, 1/2] \\ G(2s-1, t) & s \in [1/2, 1]. \end{cases}$$

Then to prove that H is a path homotopy between $f * g$ and $f' * g'$.

Now if $F : I \times I \rightarrow X$ then it is defined by

$$\begin{aligned} F(s, 0) &= f(x) & \text{and} & & F(s, 1) &= f'(x) \\ F(0, t) &= x_0 & & & F(1, t) &= x_1 \end{aligned}$$

And $G : I \times I \rightarrow X$ is a path homotopy between g and g'

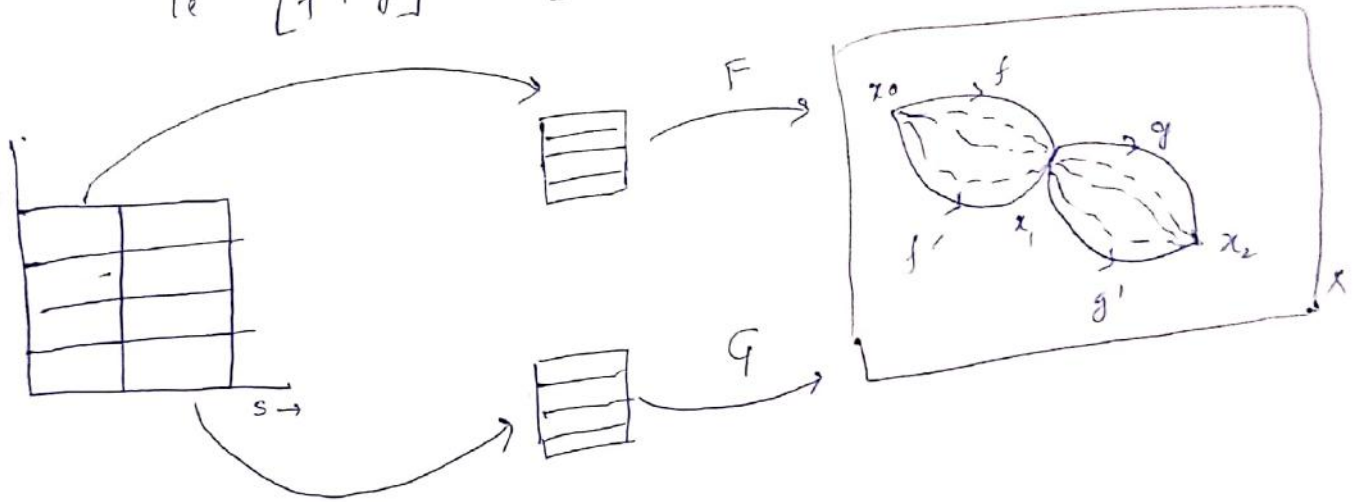
$$\begin{aligned} G(s, 0) &= g(x) & \text{and} & & G(s, 1) &= g'(x) \\ G(0, t) &= x_0 & & & G(1, t) &= x_1 \end{aligned}$$

$$\Rightarrow F(1, t) = x_1 = G(0, t)$$

New map H is well defined and is continuous by pasting lemma. Hence H is a path homotopy between $f * g$ and $f' * g'$

or $[f] * [g] = [f'] * [g']$.

ie $[f * g] = [f' * g']$.



Groupoid properties of '*'.
The properties of '* are called groupoid properties of

for the pairs $[f], [g]$ the relation holds $f(1) = g(0)$.

(i) if $[f] * ([g] * [h])$ is defined so is $([f] * [g]) * [h]$, and
 $\therefore [f] * ([g] * [h]) = ([f] * [g]) * [h]$.

(ii) $\forall x \in X$, let e_x denote the constant path $e_x: I \rightarrow X$ carrying all of I to the point x . If f is a path in X from x_0 to x_1 , then

$$[f] * [e_{x_1}] = [f]$$

and $[e_{x_0}] * [f] = [f]$.

(iii) Given the path f in X from x_0 to x_1 . Let \bar{f} be the path defined by $\bar{f}(s) = f(1-s)$. It is called reverse of f . Then

$$[f] * [\bar{f}] = [e_{x_0}]$$

$$[\bar{f}] * [f] = [e_{x_1}]$$

Def Let X be a space and $x_0 \in X$. A path in X is said to loop if it begins and ends at x_0 . Path is based at x_0 .

The set of path homotopy class of loops based at x_0 with operation $*$ is called fundamental group of X relative to the base point x_0 . It is denoted by $\pi_1(X, x_0)$.

Def The homotopy relation \simeq gives rise to a partition of the function space Y^X into disjoint equivalent classes called homotopy classes.

If (X, x_0) be the collection of closed paths then \simeq_{x_0} is an equivalence relation.

Theorem. - Show that $\pi_1(X, x_0)$ is a group.

(i) Let $[f], [g] \in \pi_1(X, x_0)$ define the operation 'o' by

$$[f] \circ [g] = [f * g].$$

We first show that 'o' is well defined.

i.e. the operation 'o' does not depend upon the representatives f and g of $[f]$ and $[g]$ used.

Suppose $f_1 \simeq_{x_0} f_2$ and $g_1 \simeq_{x_0} g_2$ then \exists homotopies h_1, h_2

such that

$$\begin{aligned} h_1(s, 0) &= f_1(s) & h_1(s, 1) &= f_2(s) \\ h_2(s, 0) &= g_1(s) & h_2(s, 1) &= g_2(s) \end{aligned} \quad \forall s \in I.$$

and

$$\begin{aligned} h_1(0, t) &= h_1(1, t) = x_0 \\ h_2(0, t) &= h_2(1, t) = x_0 \end{aligned} \quad \forall t \in I$$

Define

$$h(s, t) = \begin{cases} h_1(2s, t) & \text{if } 0 \leq s \leq \frac{1}{2} \\ h_2(2s-1, t) & \text{if } \frac{1}{2} \leq s \leq 1 \end{cases}$$

Then

$$h_0\left(\frac{1}{2}, t\right) = h_1(1, t) = x_0$$

$$h_1\left(\frac{1}{2}, t\right) = h_2(0, t) = x_0$$

Hence the map h is well defined and continuous

$$\text{Also } h(s, 0) = \begin{cases} h_1(2s, 0) = f_1(2s) & s \in [0, \frac{1}{2}] \\ h_2(2s-1, 0) = g_1(2s-1) & s \in [\frac{1}{2}, 1] \end{cases}$$

$$\text{Thus } h(s, 0) = (f_1 * g_1)(s) \quad s \in [0, \frac{1}{2}]$$

$$\text{Again } h(s, 1) = \begin{cases} h_1(2s, 1) = f_2(2s) & s \in [0, \frac{1}{2}] \\ h_2(2s-1, 1) = g_2(2s-1) & s \in [\frac{1}{2}, 1] \end{cases}$$

$$\therefore h(s, 1) = (f_2 * g_2)(s)$$

$$\text{Also } h(0, t) = h_1(0, t) = x_0$$

$$\text{and } h(1, t) = h_2(1, t) = x_0$$

$$\Rightarrow f_1 * g_1 \simeq_{x_0} f_2 * g_2$$

ie if $f_1 \simeq_{x_0} f_2$ and $g_1 \simeq_{x_0} g_2$ then

$$f_1 * g_1 \simeq_{x_0} f_2 * g_2 \text{ and 'o' is well defined.}$$

$$\text{ie } f * g \in \mathbb{A}_1(X, x_0) \text{ ie } [f] \circ [g] \in \Pi_1(X, x_0)$$

ie $\Pi_1(X, x_0)$ is closed w.r.t. binary operation 'o'

(ii) let $[f], [g], [k] \in \Pi_1(X, x_0)$. Then

$$[(f * g) * k](s) = \begin{cases} (f * g)(2s) & s \in [0, \frac{1}{2}] \\ k(2s-1) & s \in [\frac{1}{2}, 1] \end{cases}$$

if $0 \leq s \leq \frac{1}{2}$ ie $0 \leq 2s \leq 1$ so that

$$\begin{aligned} (f * g)(2s) &= \begin{cases} f(2 \cdot 2s) & 0 \leq 2s \leq \frac{1}{2} \\ g(2 \cdot (2s-1)) & \frac{1}{2} \leq 2s \leq 1 \end{cases} \\ &= \begin{cases} f(4s) & 0 \leq s \leq \frac{1}{4} \\ g(4s-1) & \frac{1}{4} \leq s \leq \frac{1}{2} \end{cases} \end{aligned}$$

$$\therefore ((f * g) * k)_s = \begin{cases} f(4s) & s \in [0, \frac{1}{4}] \\ g(4s-1) & s \in [\frac{1}{4}, \frac{1}{2}] \\ h(2s-1) & s \in [\frac{1}{2}, 1] \end{cases}$$

Similarly

$$(f * (g * k))_s = \begin{cases} f(2s) & s \in [0, \frac{1}{2}] \\ (g * k)(2s-1) & s \in [\frac{1}{2}, 1] \end{cases}$$

If $\frac{1}{2} \leq s \leq 1$ then $0 \leq 2s-1 \leq 1$

$$\begin{aligned} \therefore (g * k)(2s-1) &= \begin{cases} g(2(2s-1)) & 0 \leq 2s-1 \leq \frac{1}{2} \\ k(2(2s-1)-1) & \frac{1}{2} \leq 2s-1 \leq 1 \end{cases} \\ &= \begin{cases} g(4s-2) & \frac{1}{2} \leq s \leq \frac{3}{4} \\ k(4s-3) & \frac{3}{4} \leq s \leq 1 \end{cases} \end{aligned}$$

$$\Rightarrow (f * (g * k))_s = \begin{cases} f(2s) & s \in [0, \frac{1}{2}] \\ g(4s-2) & \frac{1}{2} \leq s \leq \frac{3}{4} \\ k(4s-3) & \frac{3}{4} \leq s \leq 1 \end{cases}$$

Define $h : I \times I \rightarrow X$ by

$$h(s, t) = \begin{cases} f\left(\frac{4s}{t+1}\right) & t \geq 4s-1 \\ g\left(\frac{4s-t-1}{2-t}\right) & 4s-1 \geq t \geq 4s-2 \\ k\left(\frac{4s-t-2}{2-t}\right) & 4s-2 \geq t \end{cases}$$

Then by pasting lemma function is continuous

$$h(s, 0) = \begin{cases} f(4s) \\ g(4s-1) \\ k(2s-1) \end{cases}$$

$$h(s, 1) = \begin{cases} f(2s) \\ g(4s-2) \\ k(4s-3) \end{cases}$$

ie $h(s, 0) = ((f * g) * k)(s)$

$$h(s, 1) = (f * (g * k))(s)$$

Also $h(0, t) = f(0) = x_0$

$$h(1, t) = k(1) = x_0$$

$$\Rightarrow (f * g) * k \stackrel{\cong}{\simeq} x_0 \quad f * (g * k)$$

$$\Rightarrow ([f] \circ [g]) \circ [k] = [f] \circ ([g] \circ [k]).$$

(iii) Let $e_{x_0} : I \rightarrow \{x_0\}$ be a constant map. To show that

$[e_{x_0}]$ is the identity element of $\pi_1(X, x_0)$.

Let $[f] \in \pi_1(X, x_0)$. Then $f(1) = x_0$.

Define $H : I \times I \rightarrow X$ by

$$H(s, t) = \begin{cases} f\left(\frac{2s}{1+t}\right), & t \geq 2s-1 \\ x_0, & t \leq 2s-1 \end{cases}$$

Then H is continuous for when $t = 2s-1$

$$H(s, 2s-1) = f(1) = x_0$$

$$H(s, 2s+1) = x_0$$

Also $H(s, 0) = \begin{cases} f(2s) \\ x_0 \end{cases}$

$$s \in [0, \frac{1}{2}]$$

$$s \in [\frac{1}{2}, 1]$$

But $e_{x_0}(2s-1) = x_0$ by def of e_{x_0}

$$H(s, 0) = \begin{cases} f(2s) & s \in [0, \frac{1}{2}] \\ e_{x_0}(2s-1) & s \in [\frac{1}{2}, 1] \end{cases}$$

$$\therefore H(s, 0) = (f * e_{x_0})(s)$$

Again Similarly $H(s, 1) = f(s), \quad 0 \leq s \leq 1$

Also $H(0, t) = f(0) = x_0, \quad H(1, t) = x_0$

So that $f * e_{x_0} \simeq_{x_0} f$

" $[f] \circ [e_{x_0}] = [f]$

Similarly $[e_{x_0}] \circ [f] = [f]$.

$\Rightarrow e_{x_0}$ is the identity element of $\Pi_1(X, x_0)$

(IV) Let $[f] \in \Pi_1(X, x_0)$. Define a map \bar{f} by $\bar{f}(s) = f(1-s)$

Then $\bar{f}(0) = f(1) = x_0$ and $\bar{f}(1) = f(0) = x_0$.

Hence $\bar{f} \in C(X, x_0)$ the set of closed paths.

New $(f * \bar{f})(s) = \begin{cases} f(2s) & s \in [0, \frac{1}{2}] \\ \bar{f}(2s-1) & s \in [\frac{1}{2}, 1] \end{cases}$

$$= \begin{cases} f(2s) & s \in [0, \frac{1}{2}] \\ f(2-2s) & s \in [\frac{1}{2}, 1] \end{cases}$$

Now define a map $H: I \times I \rightarrow X$ by

$$H(s, t) = \begin{cases} x_0 & 0 \leq s \leq \frac{t}{2} \\ f(2s-t) & \frac{t}{2} \leq s \leq \frac{1}{2} \\ \bar{f}(2s+t-1) & \frac{1}{2} \leq s \leq 1 - \frac{t}{2} \\ x_0 & 1 - \frac{t}{2} \leq s \leq 1. \end{cases}$$

* $s, t \in I$. Then by continuity of H follows from the continuity of f and \bar{f} .

$$\therefore H(s, 0) = \begin{cases} f(2s) & 0 \leq s \leq \frac{1}{2} \\ \bar{f}(2s-1) & \frac{1}{2} \leq s \leq 1 \end{cases}$$

and $H(s, 1) = x_0 \quad \forall 0 \leq s \leq 1.$

Therefore $H(s, 0) = (f * \bar{f})(s)$

$$H(s, 1) = e_{x_0}(s) = x_0.$$

Also $H(0, t) = x_0 = H(1, t)$

$$\Rightarrow f * \bar{f} \simeq_{x_0} e_{x_0}$$

Similarly $\bar{f} * f \simeq_{x_0} e_{x_0}$

i.e. \bar{f} is the inverse of f

Hence $\Pi_1(X, x_0)$ is a group.

$\Pi_1(X, x_0, \circ)$ is called first homotopy group or Poincaré gr.

Examples. (1) If R^n is euclidean n -space. Then $\Pi_1(R^n, x_0)$ is a trivial group (the group consisting the identity alone)

For, if f is a loop in R^n based at x_0 the straight line homotopy is a path homotopy between f and the constant-path x_0 .

If X is any convex set of R^n then $\Pi_1(X, x_0)$ is a trivial group.

If B^n is a unit ball in R^n where

$$B^n = \{x : x_1^2 + x_2^2 + \dots + x_n^2 \leq 1\}$$

has a fundamental trivial group.

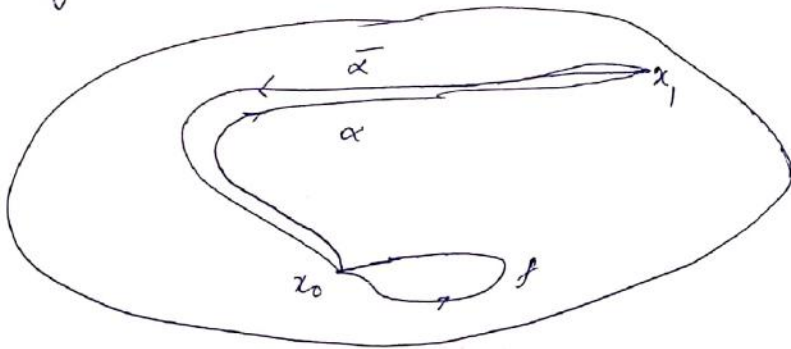
Def. Let α be a path in X from x_0 to x_1 . Define a map

$$\hat{\alpha} : \pi_1(X, x_0) \longrightarrow \pi_1(X, x_1)$$

by the equation

$$\hat{\alpha}([f]) = [\bar{\alpha}] * [f] * [\alpha]$$

The map $\hat{\alpha}$ is well defined because $*$ is well defined. If f is loop based at x_0 then $\bar{\alpha} * (f * \alpha)$ is a loop based at x_1 . Hence $\hat{\alpha}$ maps $\pi_1(X, x_0)$ into $\pi_1(X, x_1)$. $\hat{\alpha}$ only depends on the path homotopy class of α .



Theorem $\hat{\alpha}$ is a group isomorphism.

Proof To show that $\hat{\alpha}$ is a homomorphism, to compute

$$\begin{aligned} \hat{\alpha}([f]) * \hat{\alpha}([g]) &= ([\bar{\alpha}] * [f] * [\alpha]) * ([\bar{\alpha}] * [g] * [\alpha]) \\ &= [\bar{\alpha}] * [f] * [e_{x_0}] * [g] * [\alpha] \\ &= [\bar{\alpha}] * [f] * [g] * [\alpha] \\ &= [\bar{\alpha}] * [f * g] * [\alpha] \\ &= \hat{\alpha}([f * g]) = \hat{\alpha}([f] * [g]). \end{aligned}$$

To show that $\hat{\alpha}$ is an isomorphism, we want to show that if β denotes the path $\bar{\alpha}$, which is the reverse of α then $\hat{\beta}$ is an inverse for $\hat{\alpha}$. So to compute $\hat{\beta} \circ \hat{\alpha}$ for $[h] \in \pi_1(X, x_0)$

$$\begin{aligned} \hat{\beta}([h]) &= [\bar{\beta}] * [h] * [\beta] = [\alpha] * [h] * [\bar{\alpha}] \\ \hat{\alpha}(\hat{\beta}([h])) &= \bar{\alpha} * [\alpha] * [h] * \bar{\alpha} * [\alpha] = [h]. \end{aligned}$$

Similarly to show that

$$\begin{aligned} \hat{\beta}(\hat{\alpha}([f])) &= [\bar{\beta}] * [\bar{\alpha}] * [f] * [\alpha] * [\beta] \\ &= [\alpha] * [\bar{\alpha}] * [f] * [\alpha] * [\bar{\alpha}] = [f]. \end{aligned}$$

$$* [f] \in \pi_1(X, x_0)$$

Hence $\hat{\beta}$ is the inverse of $\hat{\alpha}$
 $\Rightarrow \hat{\alpha}$ is a group isomorphism.

Path connected - Let X be a path top space. $\forall x, y \in X$
 there is a path from x to y in X is said to be path connected.
 ex. let $X = \{0, 1\}$ and $\tau = \{X, \emptyset, \{0\}\}$ then X is path connected if $f: I \rightarrow X$ is defined by

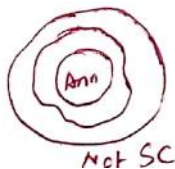
$$f(t) = \begin{cases} 0 & \text{if } t \in [0, 1) \\ 1 & \text{if } t = 1 \end{cases}$$

2. Indiscrete space is path connected.
3. Every path connected space is connected.

Corollary - If X is path connected and x_0 and x_1 are two points of X
 then $\pi_1(X, x_0)$ is isomorphic to $\pi_1(X, x_1)$.

Definition - A space X is said to be simply connected if it is a path connected space and if $\pi_1(X, x_0)$ is the trivial one element group for some $x_0 \in X$, and hence for every $x_0 \in X$, $\pi_1(X, x_0)$ is the trivial group by writing $\pi_1(X, x_0) = 0(e_{x_0})$.

Def - A topological space X is said to be simply connected if every closed path in X is contractible to a point.
 ex. In the Euclidean Plane, \mathbb{R}^2 , an open disc is simply conn. but annulus is not.



Since there are closed curves which are not contractible to a point.

Lemma. In a simply connected space X , any two paths having same initial and final points are path homotopic.

Proof - Let α, β be two paths from x_0 to x_1 in X . Then $\alpha * \bar{\beta}$ is defined and a loop in X based at x_0 . Since X is simply connected, this loop is path homotopic to constant loop at x_0 .

$$\begin{aligned} \text{i.e. } [\alpha * \bar{\beta}] &= [e_{x_0}] \\ [\alpha * \bar{\beta}] * [\beta] &= [e_{x_0}] * [\beta] \\ \Rightarrow [\alpha] * [\bar{\beta}] * [\beta] &= [e_{x_0}] * [\beta] \\ [\alpha] &= [\beta] \quad \Rightarrow \alpha \simeq \beta. \end{aligned}$$

Def Let $h: (X, x_0) \rightarrow (Y, y_0)$ be a continuous map

Define $h_*: \pi_1(X, x_0) \rightarrow \pi_1(Y, y_0)$

by the equation $h_*([f]) = [h \circ f]$.

The map h_* is well defined, for if F is path homotopy between f & f' then $h \circ F$ is a path homotopy between the paths $h \circ f$ & $h \circ f'$.

$$\begin{aligned} \text{or } F(s, 0) &= f(s) & F(s, 1) &= f'(s) \\ F(0, t) &= x_0 & F(1, t) &= x_1 \end{aligned}$$

$$\text{and } \left. \begin{aligned} (h \circ F)(0, 0) &= (h \circ f)(0) \\ (h \circ F)(1, 0) &= (h \circ f')(1) \end{aligned} \right\} \begin{aligned} (h \circ F)(0, t) &= x_0 \\ (h \circ F)(1, t) &= x_1 \end{aligned}$$

where f and f' are paths in X from x_0 to x_1 .

h_* is a homomorphism follows from the equation

$$(h \circ f) * (h \circ g) = h \circ (f * g)$$

h_* depends not only on the map $h: X \rightarrow Y$ but also on the choice of the base point x_0 . (Once x_0 is chosen, y_0 is determined by h).

If x_0 and x_1 are two different base points of X then it is not possible to use h_* for two different homomorphisms; since one having the domain $\pi_1(X, x_0)$ and other having domain $\pi_1(X, x_1)$. If X is path connected then groups are isomorphic they are still not same group. In that case,

$$(h_{x_0})_* : \pi_1(X, x_0) \longrightarrow \pi_1(Y, y_0)$$

for first homomorphism

and $(h_{x_1})_*$ for the second homomorphism

If there is only one ^{base point} homomorphism then omit the base point and using h_* .

Properties of Induced homomorphisms are called Functorial properties.

Theorem. If $h: (X, x_0) \rightarrow (Y, y_0)$ and $k: (Y, y_0) \rightarrow (Z, z_0)$ are continuous maps. then

$$(k \circ h)_* = k_* \circ h_*$$

If $i: (X, x_0) \rightarrow (X, x_0)$ is a identity map then i_* is the identity homomorphism.

Proof

We know that

$$I \times I \xrightarrow[\text{Cont.}]{f} X \xrightarrow[\text{Cont.}]{h} Y \quad \text{then} \quad I \times I \xrightarrow[\text{Cont.}]{h \circ f} Y$$

$$\begin{aligned} \text{then } (h \circ f)(0) &= h(f(0)) = h(x_0) = y_0 \\ (h \circ f)(1) &= h(f(1)) = h(x_0) = y_0 \end{aligned}$$

ie hof forms a loop based at y_0

Similarly

$$I \times I \xrightarrow[\text{cont}]{g} Y \xrightarrow[\text{cont}]{k} Z \quad \text{then } [x] \xrightarrow[\text{cont}]{k \circ g} Z$$

$$(k \circ g)(0) = k(g(0)) = k(y_0) = z_0$$

$$(k \circ g)(1) = k(g(1)) = k(y_1) = z_1$$

$$\text{Now } (k \circ h)(x_0) = (k \circ h)(x_0) = k(h(x_0)) = k(y_0) = z_0$$

$$\text{let } [f] \in \pi_1(x, x_0)$$

$$\text{Then } (k \circ h)_* [f] = [(k \circ h) \circ f] = [k \circ (h \circ f)]$$

$$\begin{aligned} (k_* \circ h_*) [f] &= [k_* (h_* ([f]))] \\ &= k_* ([h \circ f]) \\ &= [k \circ (h \circ f)] \end{aligned}$$

$$\text{Hence } (k \circ h)_* [f] = (k_* \circ h_*) [f].$$

(ii) If i_x is the identity homomorphism

$$\text{then } i_x [f] = [i \circ f] = [f]$$

Therefore i_x is induced homomorphism

Corollary- If $h : (X, x_0) \rightarrow (Y, y_0)$ is a homeomorphism of X and Y

then h_* is an isomorphism of $\pi_1(X, x_0)$ with $\pi_1(Y, y_0)$

Proof - let $k : (Y, y_0) \rightarrow (X, x_0)$ be the inverse of h .

$$\text{Then } (k_* \circ h_*) [f] = (k_* \circ h_*) [f] = i_x [f] \quad \forall [f] \in \pi_1(X, x_0)$$

where i_x is the identity map. ie $i_x : (X, x_0) \rightarrow (X, x_0)$.

Similarly if $j: (Y, y_0) \rightarrow (Y, y_0)$ is an identity map

and $(h_* \circ k_*) [g] = (h_* \circ k_*) [g] = j_* [g]$

ie j_* is also an identity homomorphism.

Show k_* and j_* are the identity homomorphisms of the groups $\pi_1(X, x_0)$ and $\pi_1(Y, y_0)$ respectively

ie k_* is the inverse of h_* .

$\Rightarrow \pi_1(X, x_0)$ and $\pi_1(Y, y_0)$ are isomorphic under h_* .

Other Statement of the above Corollary -

Two topologically equivalent spaces have ^{isomorphic} fundamental groups.

Def. A topological space is said to be contractible if $\exists p \in X$ such that the identity map $i: X \rightarrow X$ is homotopic to the constant map $c: X \rightarrow [p]$. ie $i \simeq c$.

Def. A subset A of a top space X is called the retract of X iff \exists a continuous function $f: X \rightarrow A$ such that $f(x) = x \quad \forall x \in A$.

Ex \mathbb{R} is contractible

$\forall x \in \mathbb{R}$ define $h: \mathbb{R} \times I \rightarrow \mathbb{R}$ by

$$h(x, t) = (1-t)x$$

Then h is a homotopy

$$h(x, 0) = x = i(x)$$

$$h(x, 1) = 0 = c(x)$$

$\Rightarrow i \simeq c \Rightarrow$ contractible.